

# Wind Energy Converter Wake Characterization by Means of Lidar Measurements in the Context of Perdigão 2017

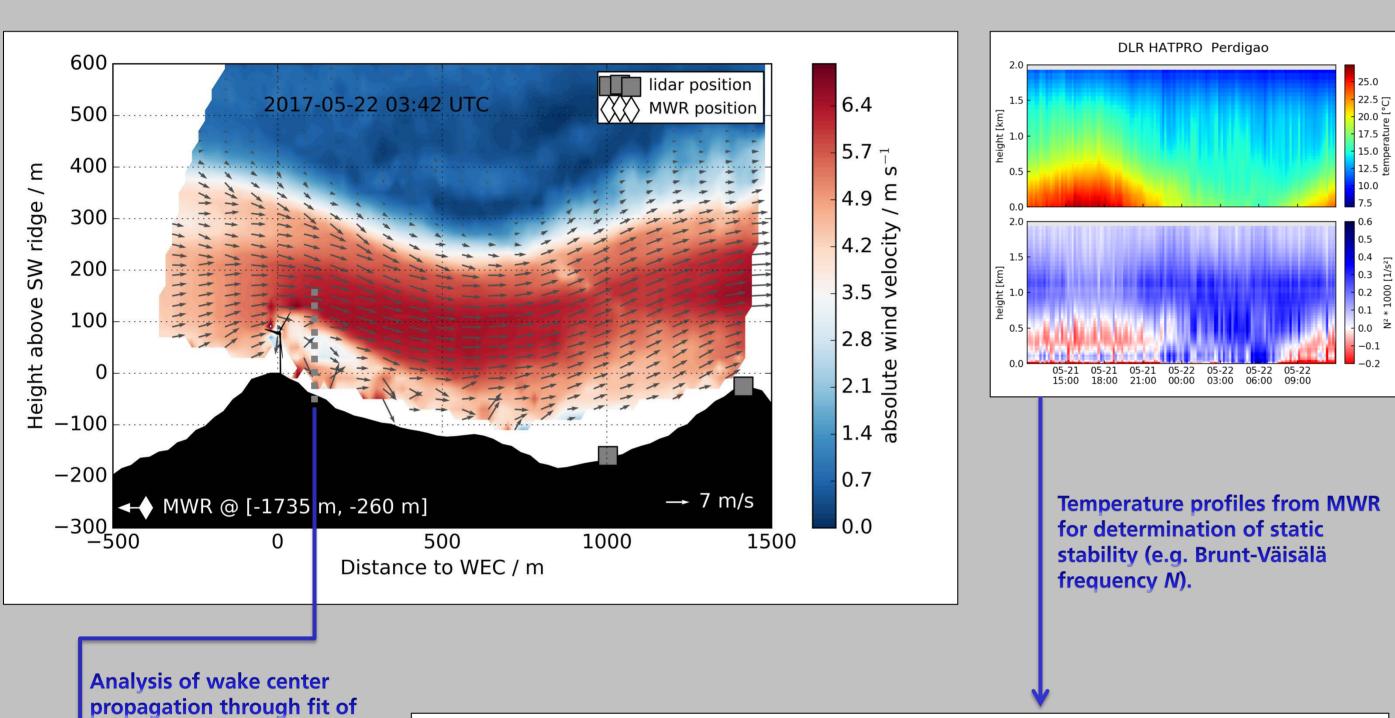
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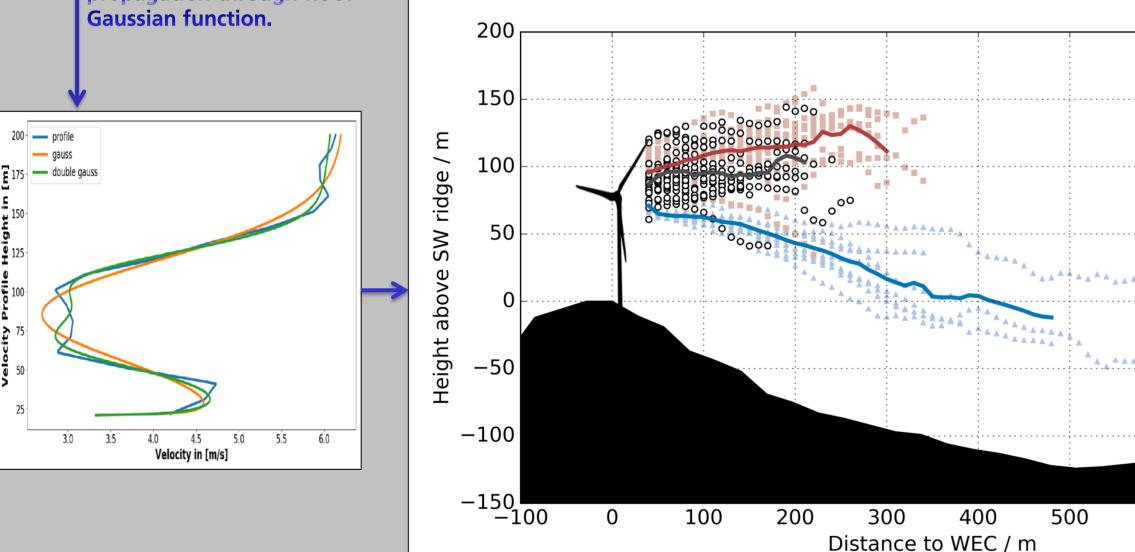
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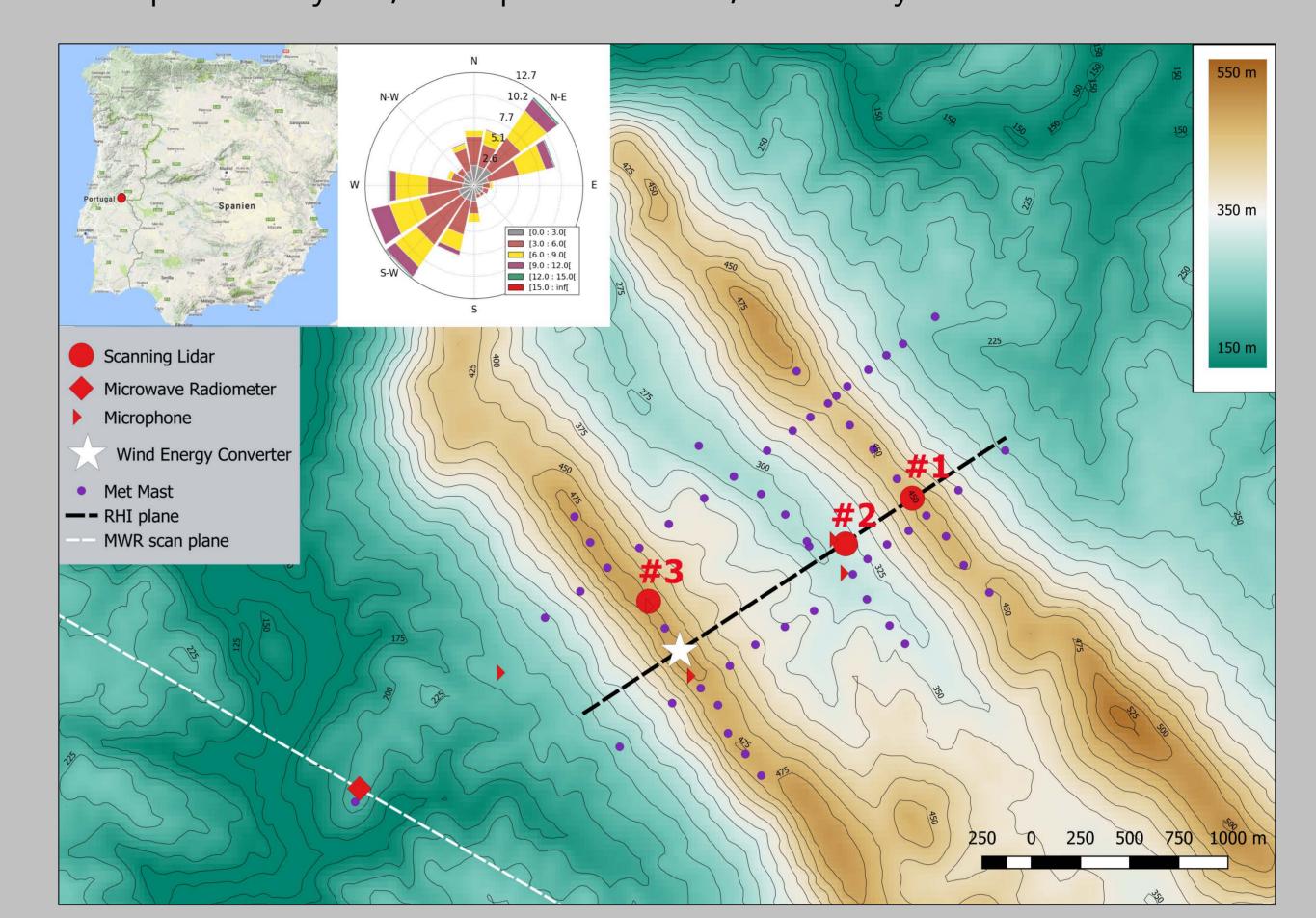
## Introduction

- Wind-energy in complex terrain is of great importance for the energy transition towards renewable energies, because it enables energy harvesting close to the consumer in many regions.
- **Perdigão 2017** was a large field campaign jointly organized by international research groups to investigate the **flow over two parallel mountain ridges** and its interaction with a single Enercon E-82 wind energy converter (WEC) placed on one of the ridges (see map on the right).
- The DLR took part with three Leosphere Windcube 2005 long-range lidar instruments, one RPG HATPRO-5G microwave radiometer (MWR) and acoustic sensors (microphones) to measure sound propagation of the WEC.









### **Coplanar RHI wake scans**

- Lidar #1 and lidar #2 were both configured to measure vertical (RHI) scans at 237° azimuth, perpendicular to the ridge and towards the WEC.
- Typical RHI parameters for lidar #1 and #2 are:

Physical resolution	25 m (100 ns pulse length, 64 point FFT)
Range gate separation	10 m
Angular resolution	0.5°
Accumulation time	500 ms
<b>Duration of one RHI</b>	1-2 minutes

• Horizontal and vertical wind of the flow in and over the valley can be calculated from the **dual-Doppler** radial wind speed measurements  $v_{ri}$  by solving the geometric equation for the meteorological wind vector u and w, where u is the horizontal wind in the scanning plane, and cross-winds are assumed to be small.

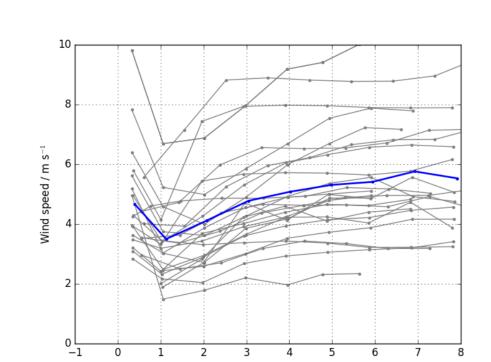
$$\begin{bmatrix} v_{r1} \\ v_{r2} \end{bmatrix} = \begin{bmatrix} \cos \varphi_1 & \sin \varphi_1 \\ \cos \varphi_2 & \sin \varphi_2 \end{bmatrix} \begin{bmatrix} u \\ w \end{bmatrix}$$

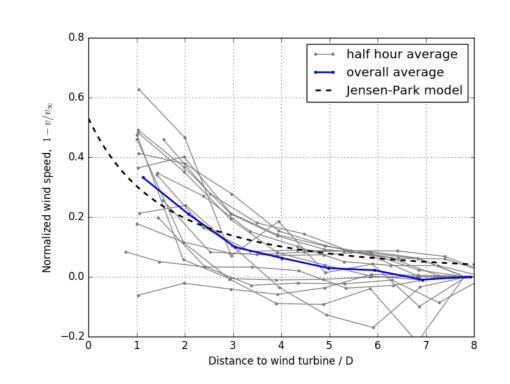
- From the coplanar scans of the wake, its **propagation path in different atmospheric conditions** can be studied (see Figures on the left).
- The wake center was tracked by fitting a superimposed **Gaussian and logarithmic function** to vertical profiles *v(z)* of wind speed downstream the WEC.

$$v(z) = A_1 \ln(b_1 z + c) - A_g e^{-\frac{(z - b_g)^2}{2\sigma^2}} + d$$

# Adaptive multi-Doppler measurement

- Coplanar scans are only useful if the wind direction is aligned with the scanning plane.
- Placing multi-Doppler measurement points in the wake (see Figure on the right) is always possible, if the wind direction is known and scanning scenarios are adapted accordingly.
- In Perdigão 2017, case studies have been done with wind direction measurements by **VAD scans** of lidar #3 and real-time data of a **sonic** anemometer on a meteorological mast close to the turbine.
- Adaptation of scanning scenario was done every 30 minutes.
- The wind speed deficit downstream the WEC can be monitored over the whole measurement period.





- Rapid decay of wind speed deficit probably due to misalignment of the measurement points with the wake.
- Improvements could be achieved by using wind turbine yaw, or a real-time wake center estimation for scanning point control.

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### Conclusion

- Multiple long-range lidar systems are a powerful tool to measure wake dynamics.
- Adaptive scenarios can increase the availability of ground-based wake measurements significantly, but need good input data.
- Best scanning strategies depend on the scientific goal, the site and the
  experimental setup. Multi-Doppler measurements with the WindScanner
  software add significant benefit and a multitude of possibilities to full-scale
  field experiments in wind-energy research.