

# **The phase diagram of soaring: flight mode transitions in combinations of isolated and aligned lift patterns**

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Winterthur, Switzerland**

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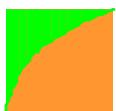
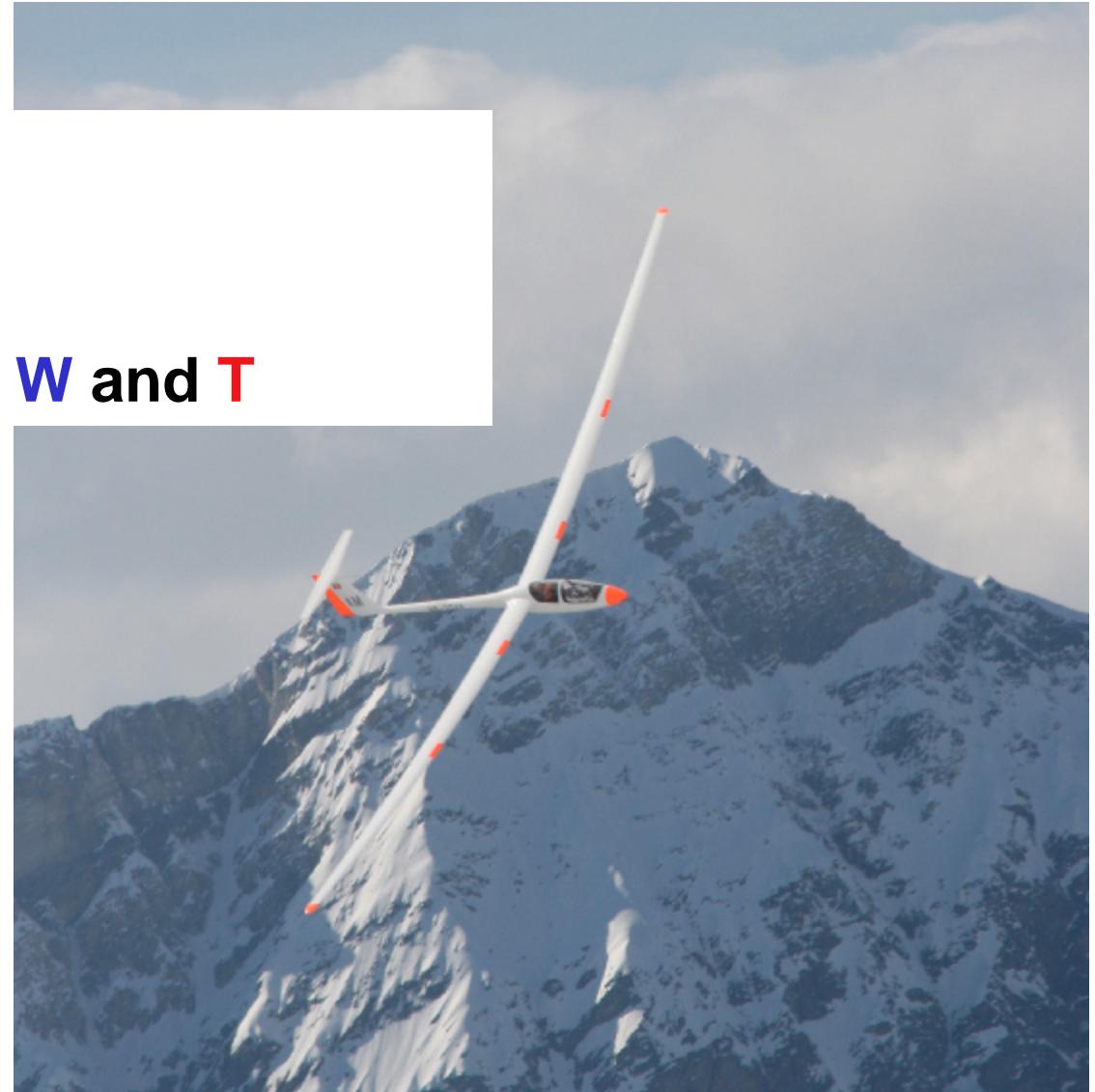
# Outline

- **Introduction**
- **PFD with **thermals****
- **PFD with **wind** and **thermals****

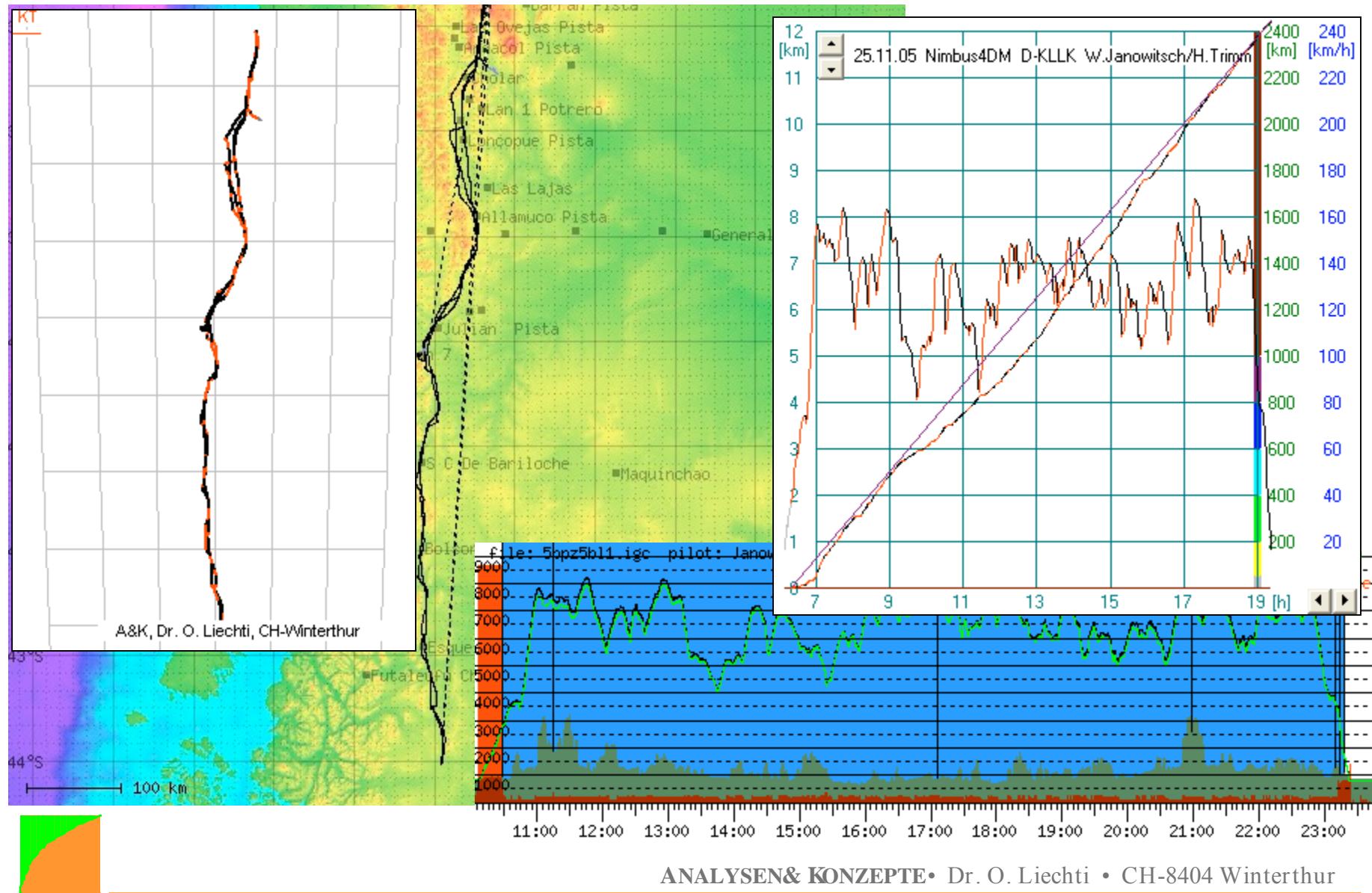


# Soaring in wind and thermals

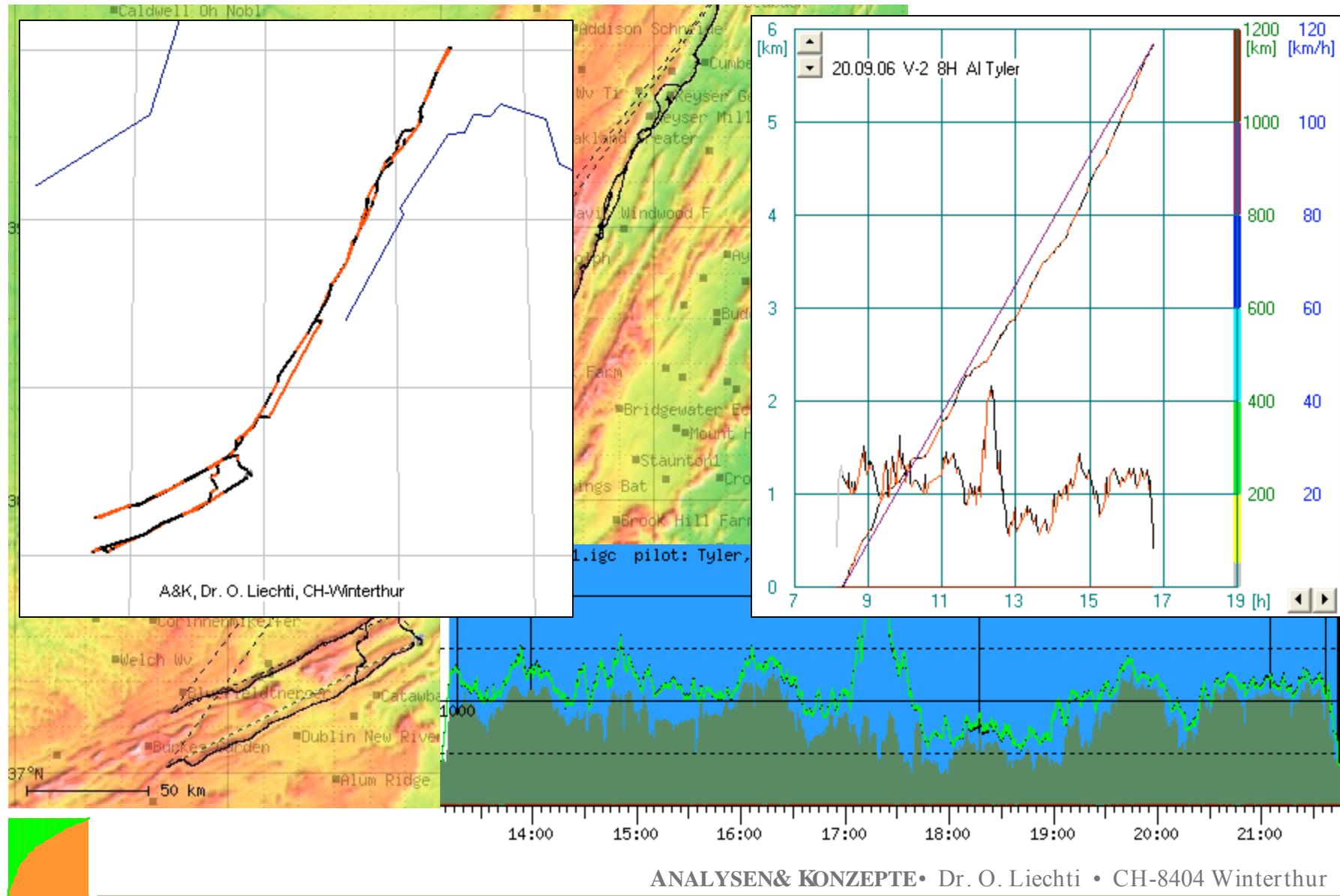
- Wave
- Ridge lift
- Thermals
- Combination of W and T



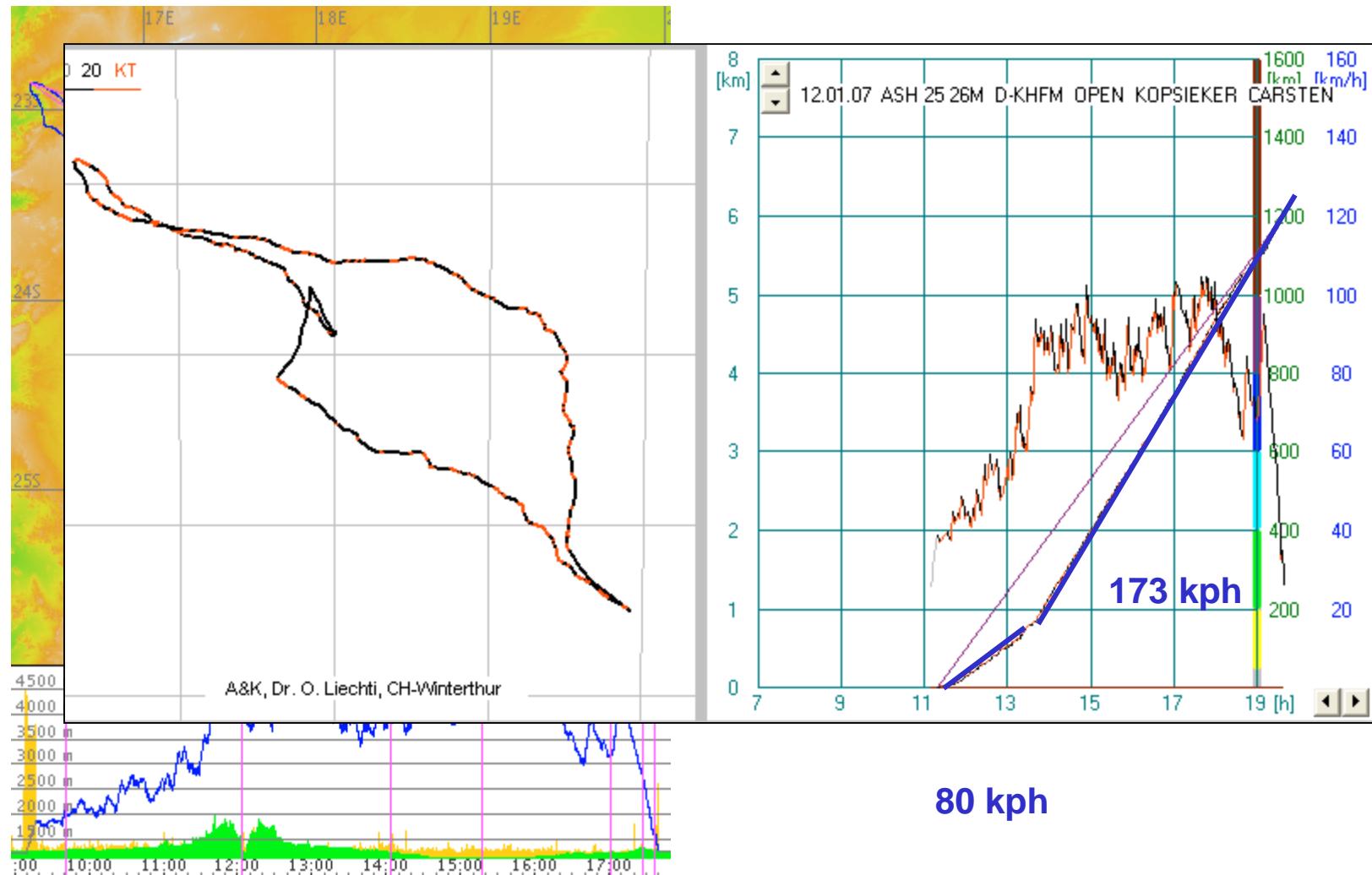
# Wave: 13 h, 2'400 km, 192 kph



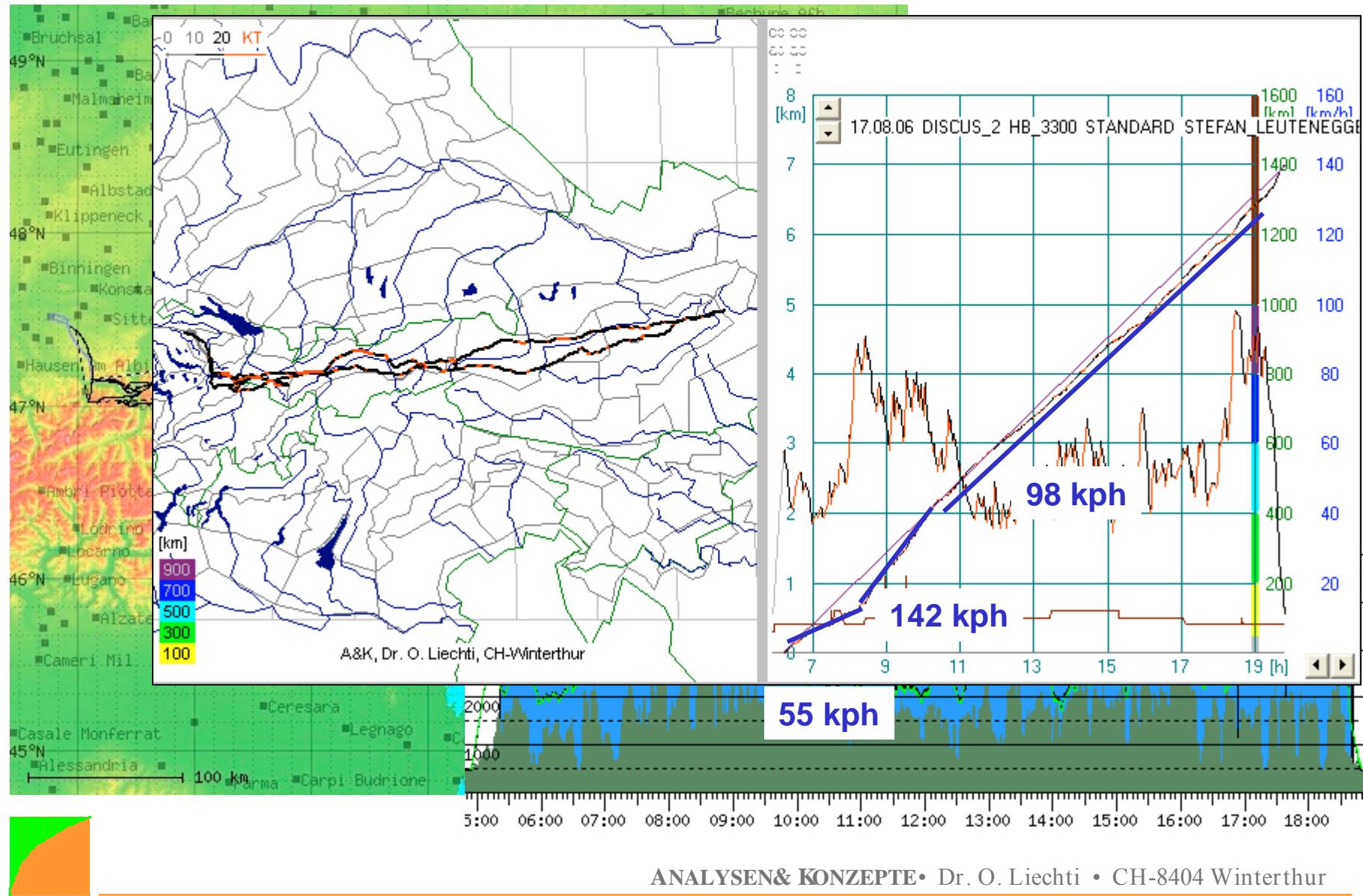
# Ridge: 8.5 h, 1'180 km, 138 kph



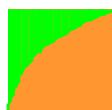
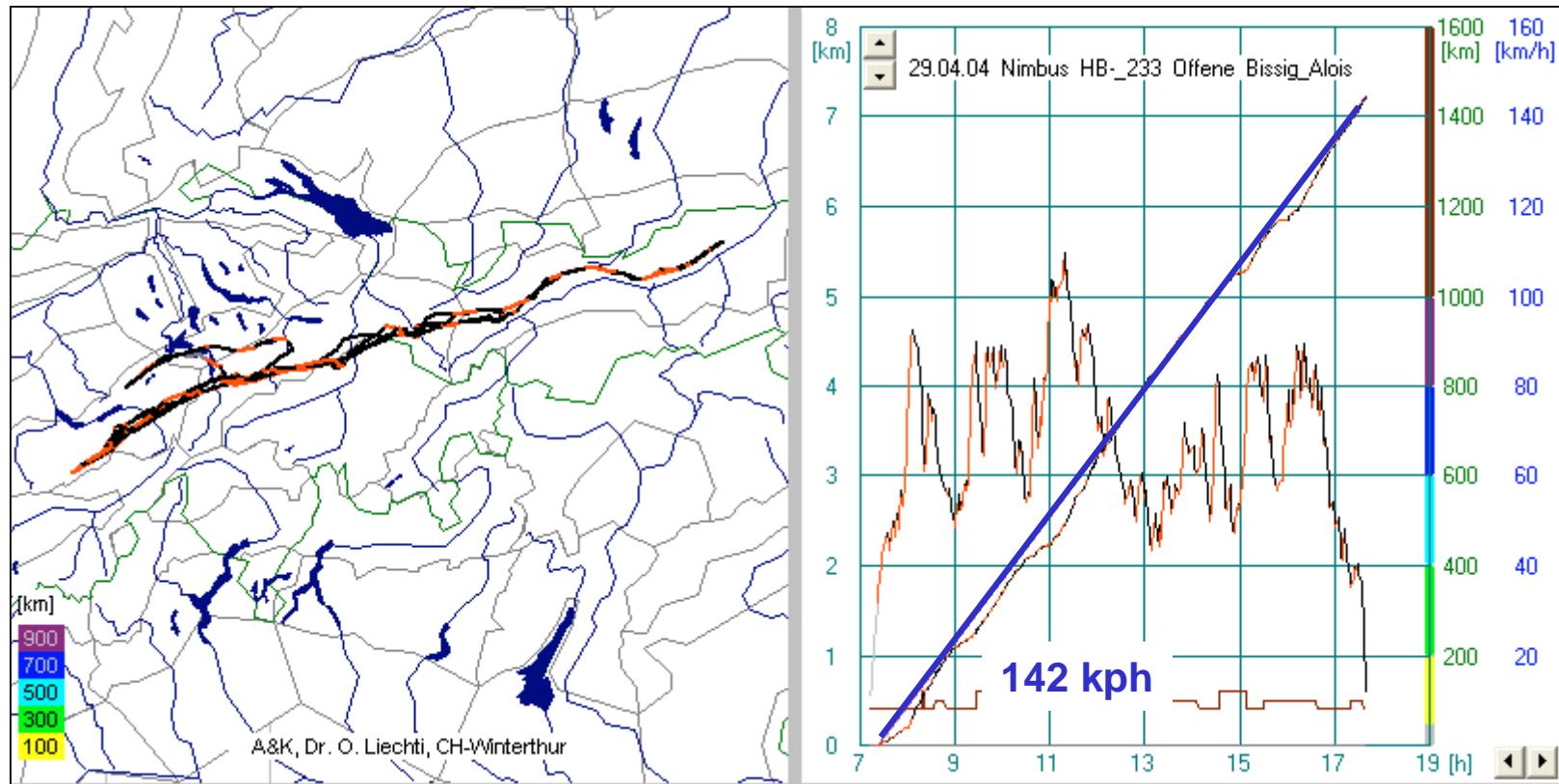
# Thermals: 7.75 h, 1'186 km, 153 kph



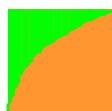
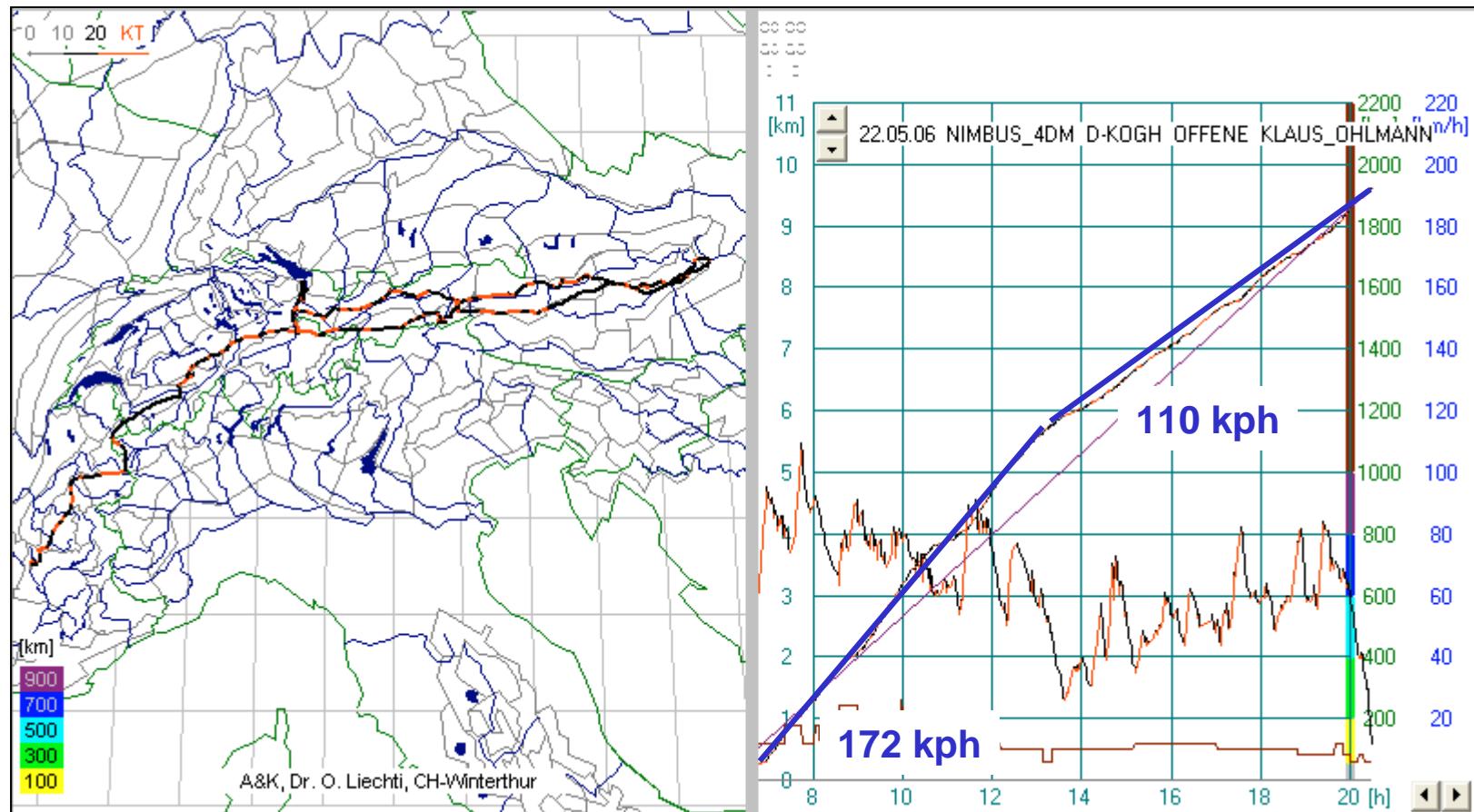
# Combination: 13.5 h, 1'400 km, 103 kph



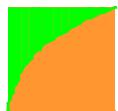
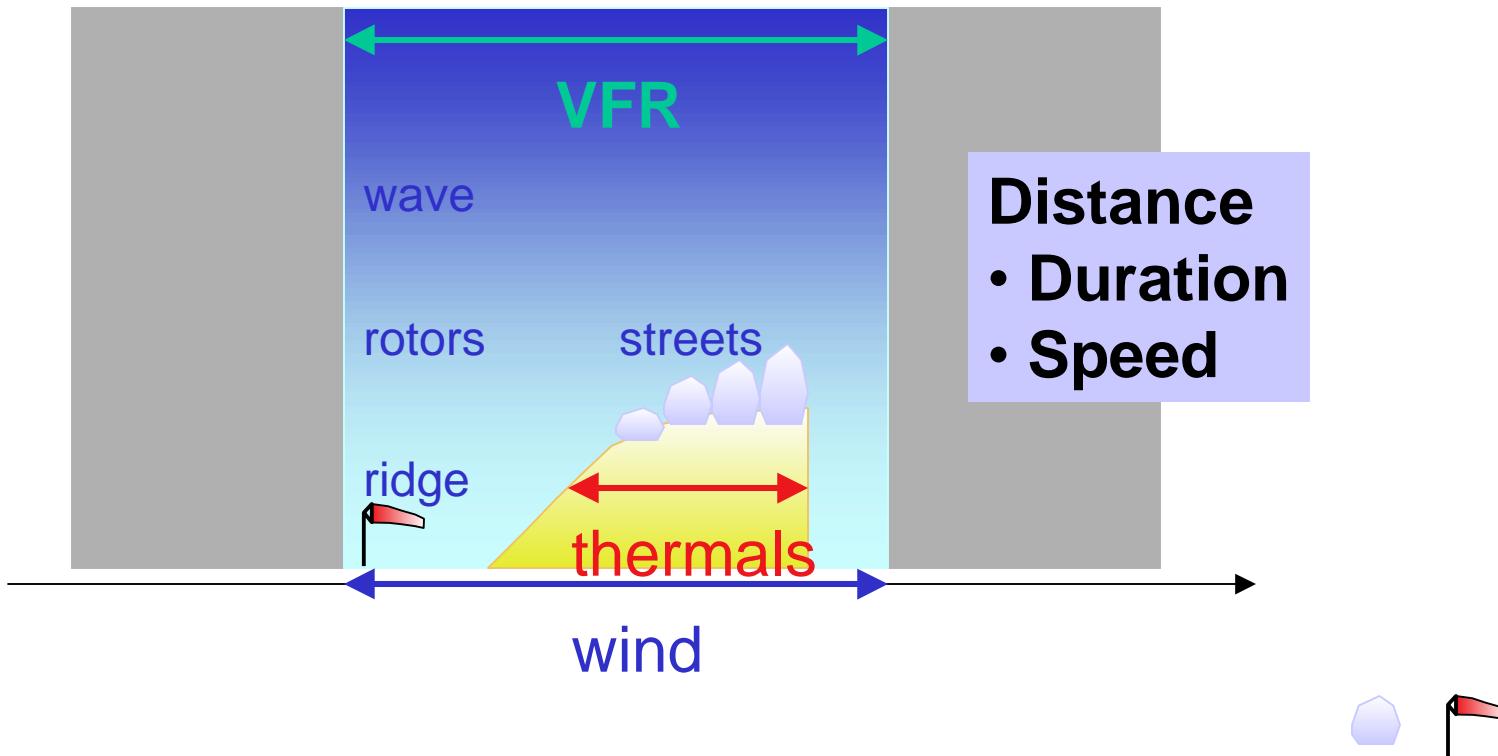
# Combination: 10.5 h, 1'430 km, 142 kph



# Combination: 14.5 h, 1'900 km, 132 kph



# Flight distance in cross-country soaring



# Soaring speed

- climb rate
- spatial lift distribution: isolated, aligned
- flight polar
- pilot skill and experience

Weather controls the duration, the strength and the spatial distribution of updrafts.

Predictions of these weather elements provide the potential flight distance (PFD).

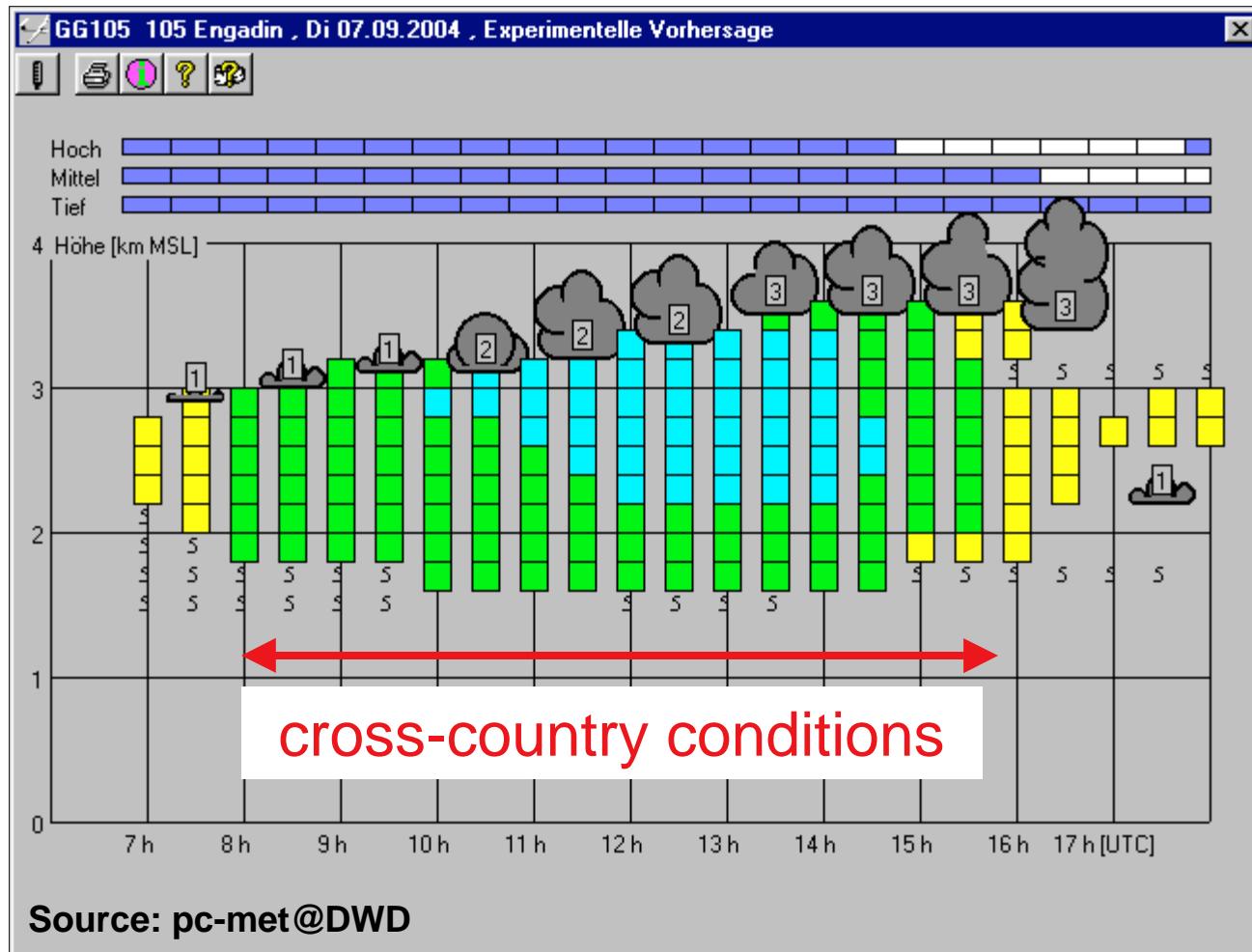


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- PFD with wind and thermals

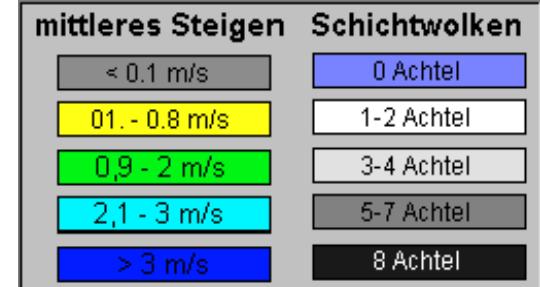


# Regional thermal forecast



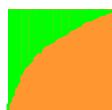
Stratiform Clouds

Cumulus Clouds



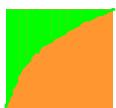
Avg. Lift

Clouds

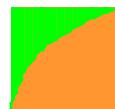
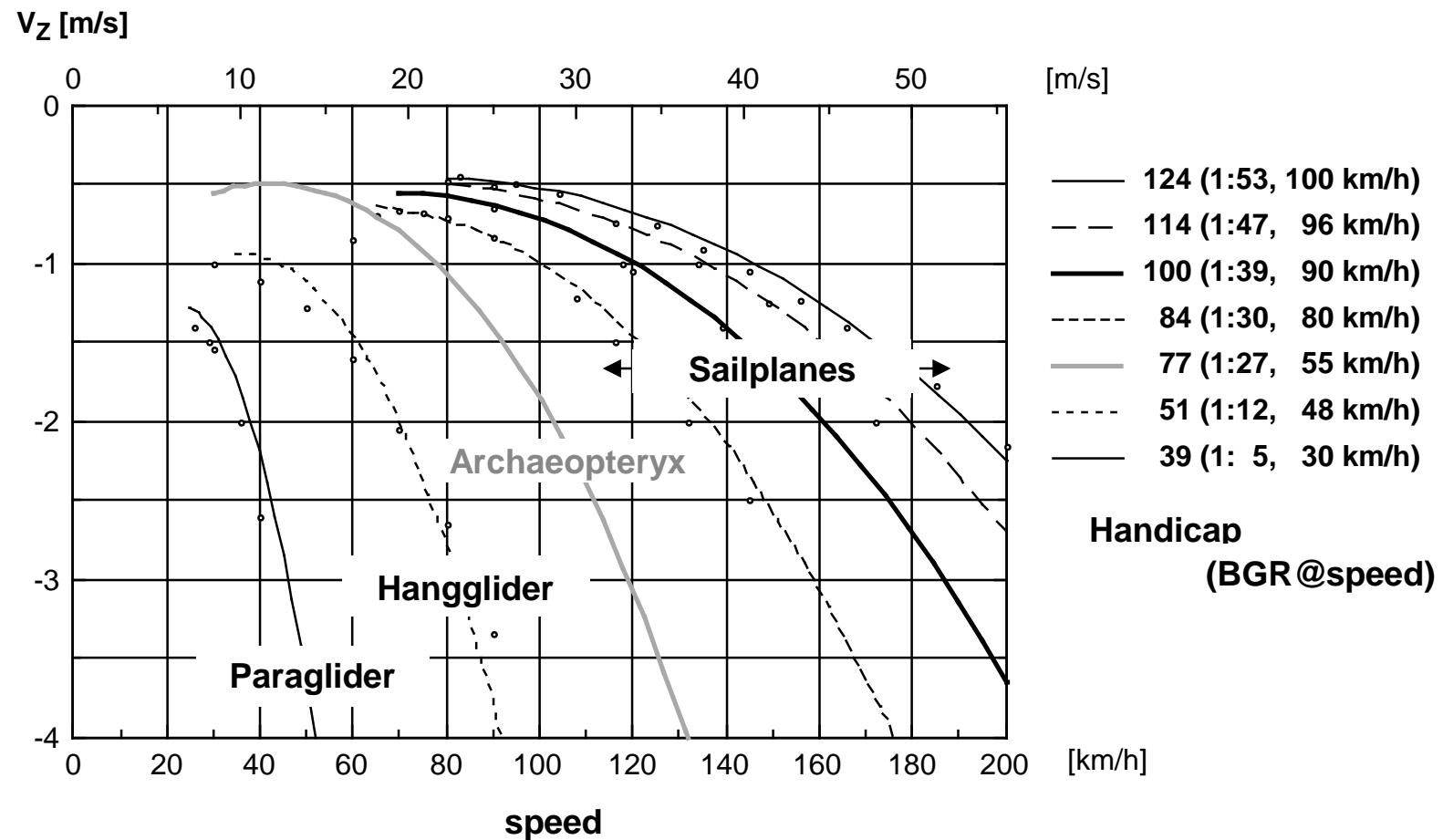


# Climb rate --> cross-country speed

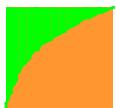
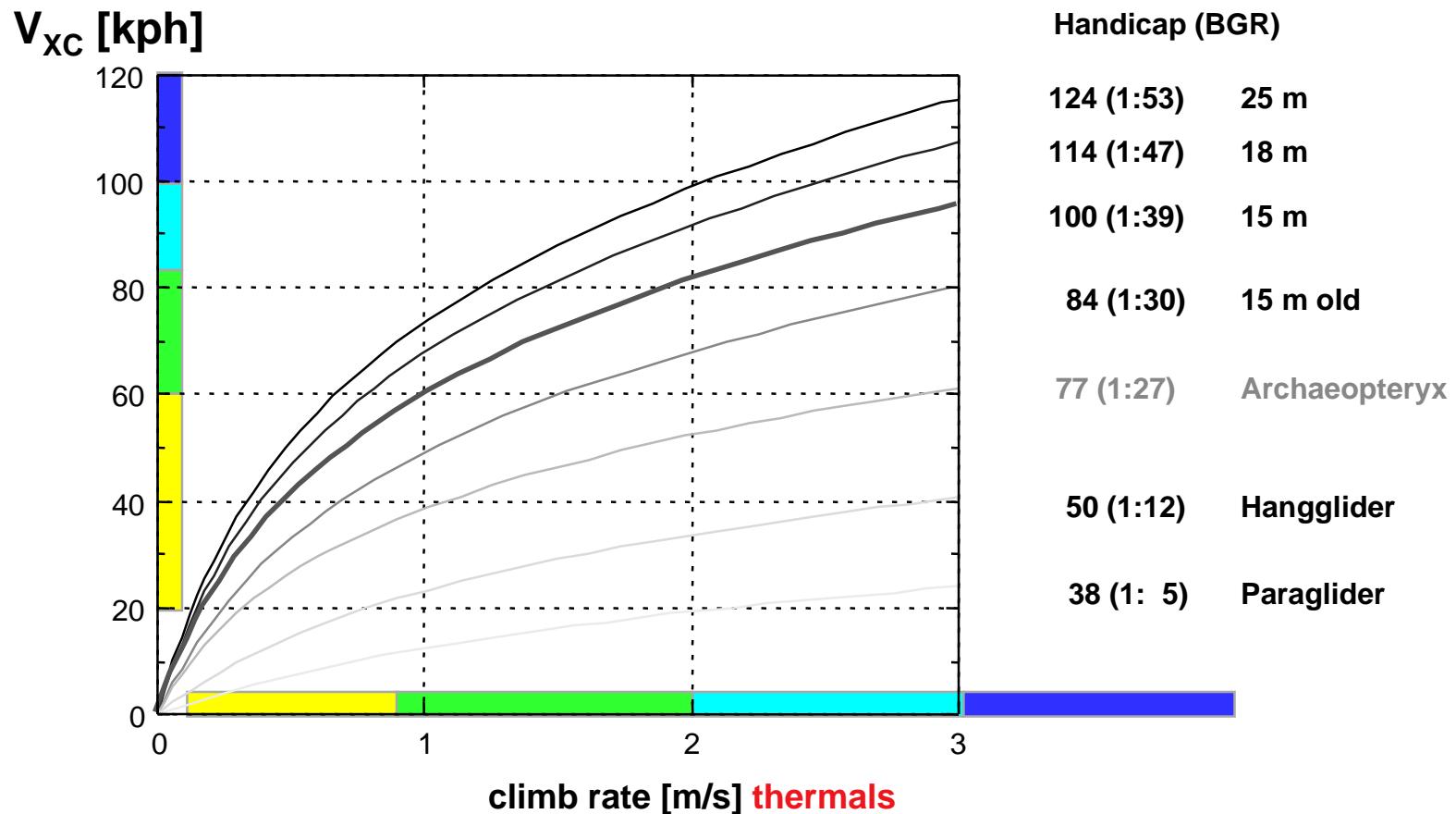
- flight polar
- speed-to-fly theory for *isolated lift*
- cross-country speed
- potential flight distance (PFD)



# Flight polar

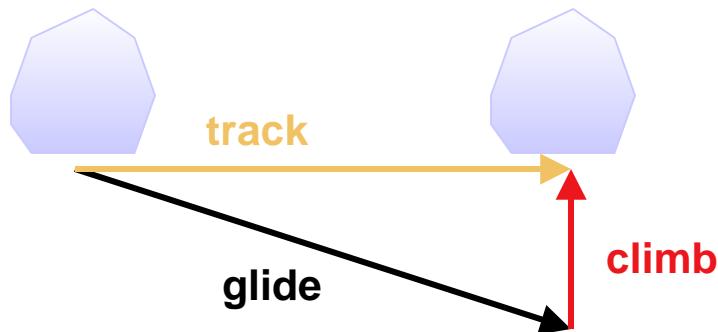


# Optimum cross-country speed

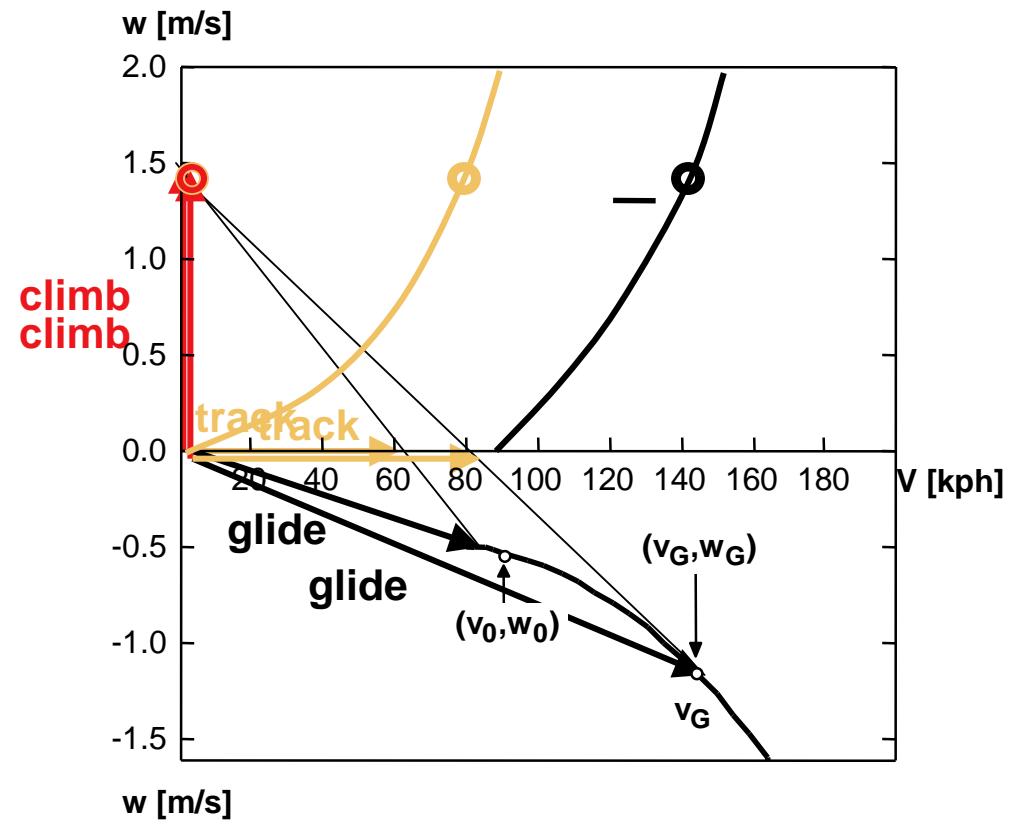


# Speed-to-fly theory

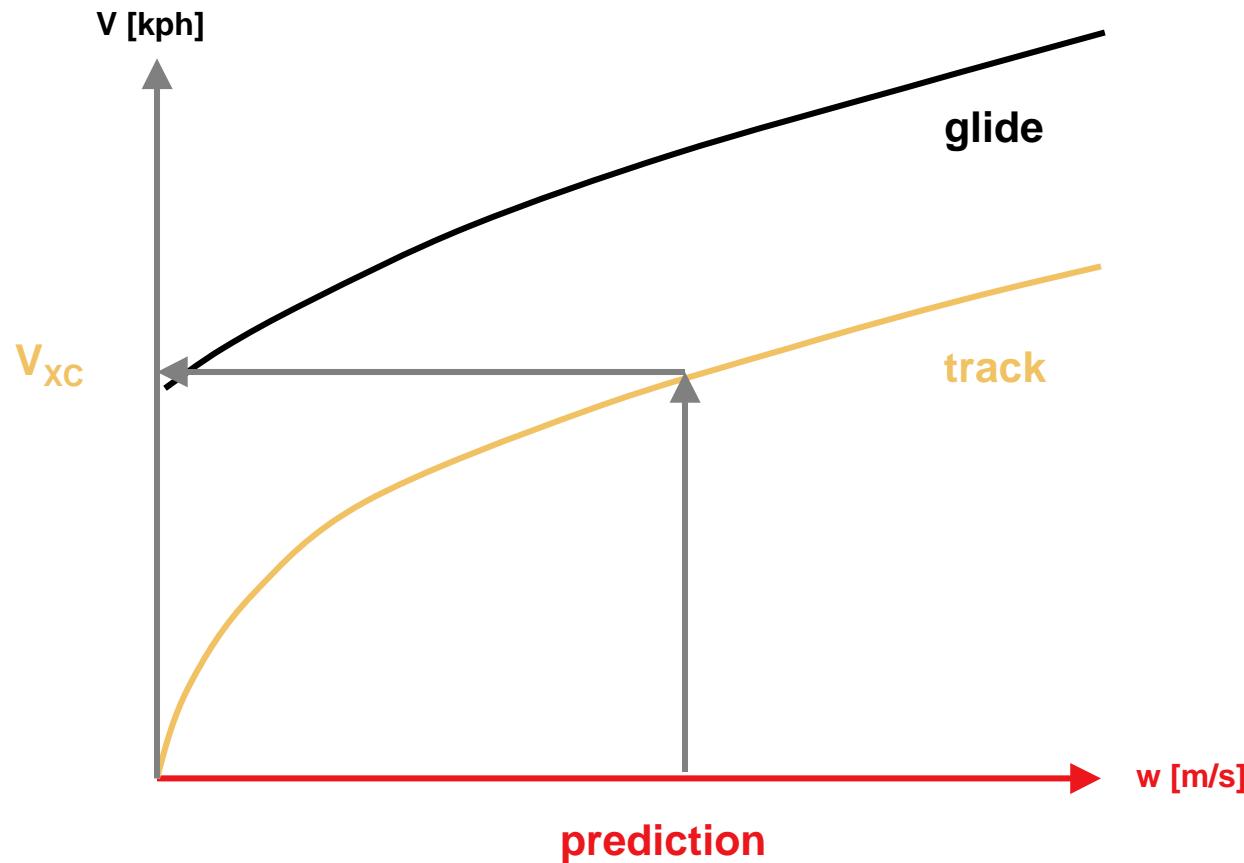
## flight path vectors



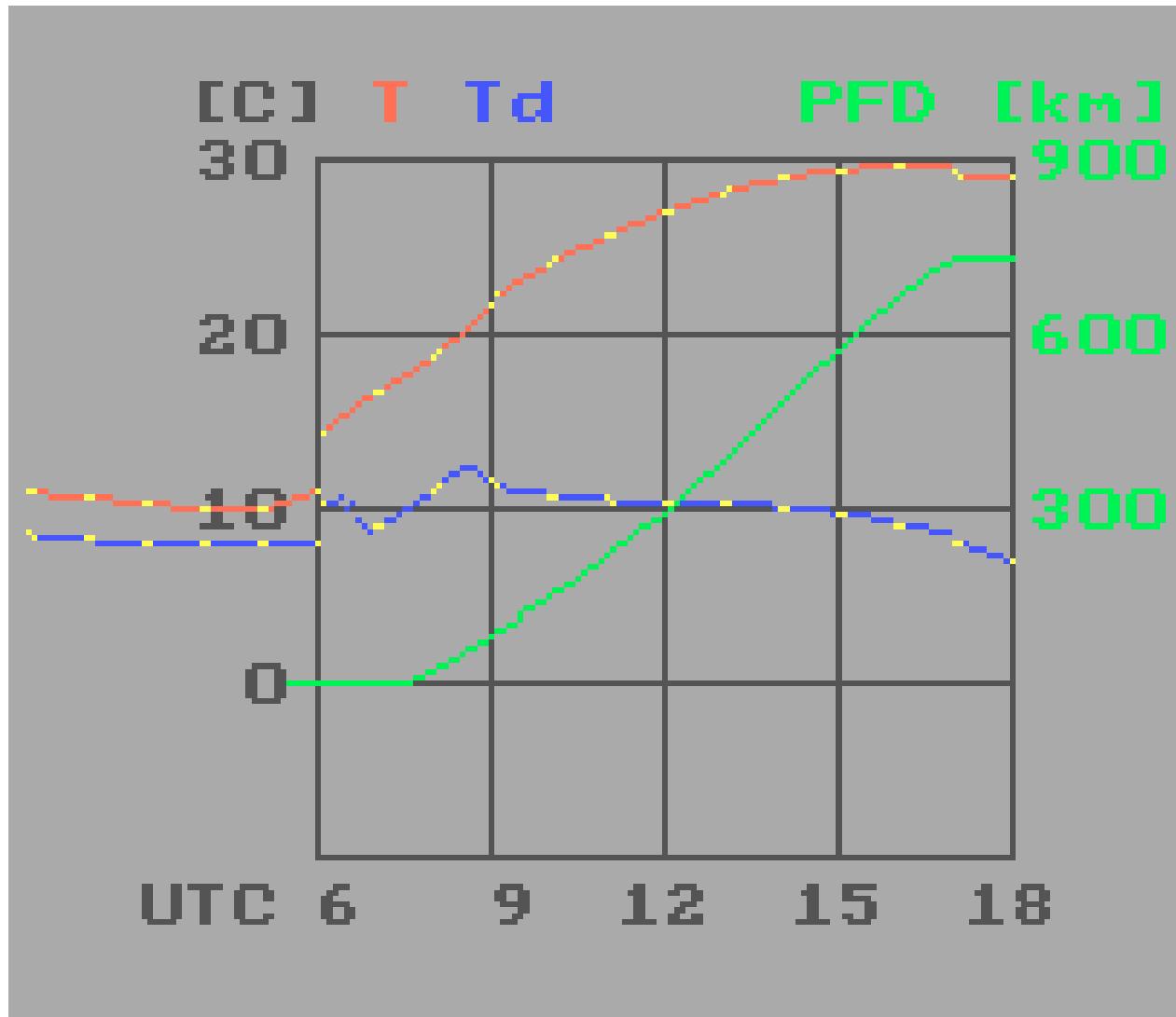
## speed vectors



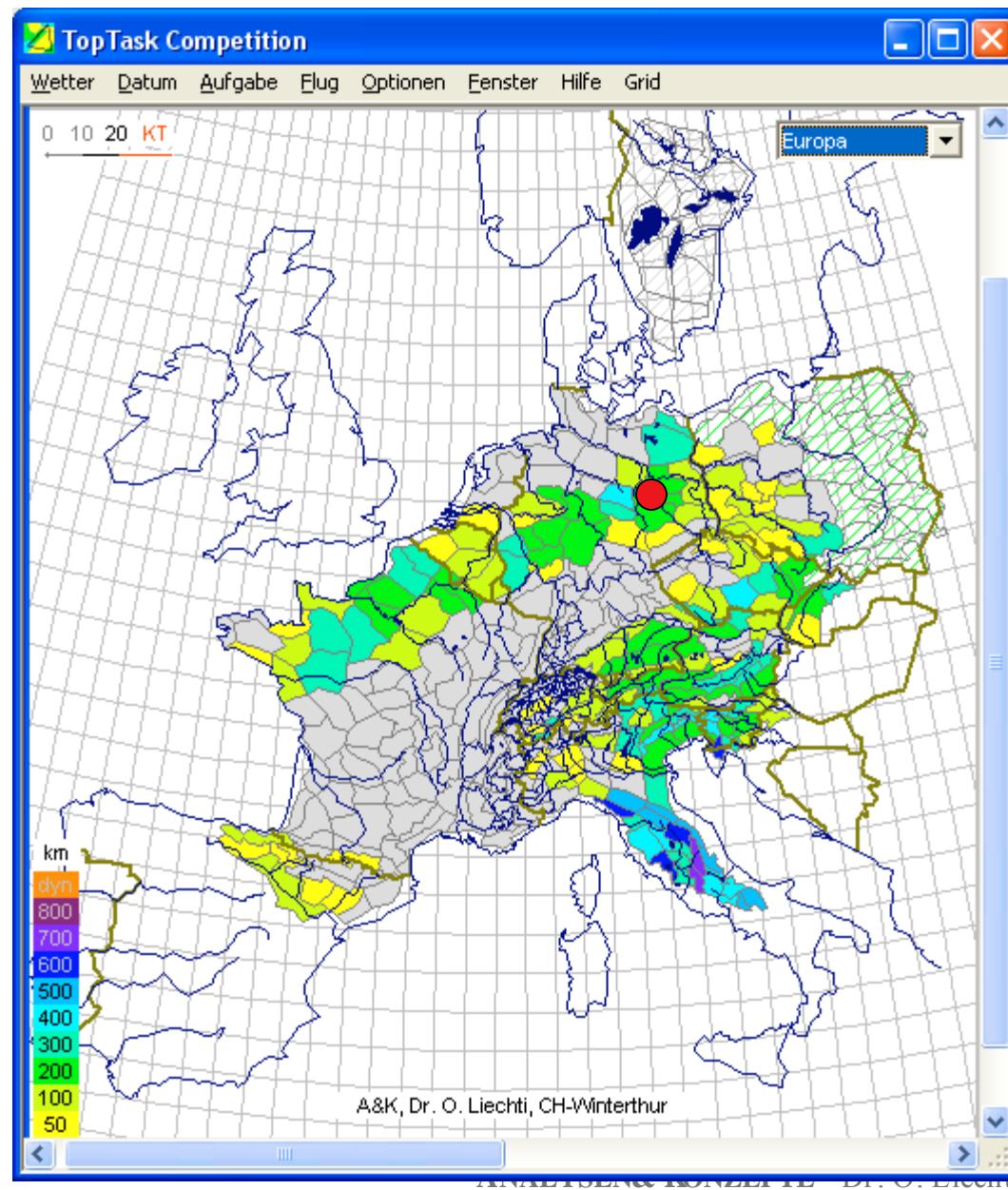
**result:  $V_{\text{Glide}}(w_{\text{Thermal}})$ ,  $V_{\text{Track}}(w_{\text{Thermal}})$**



# Potential flight distance (PFD)



# PFD map



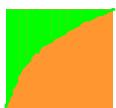
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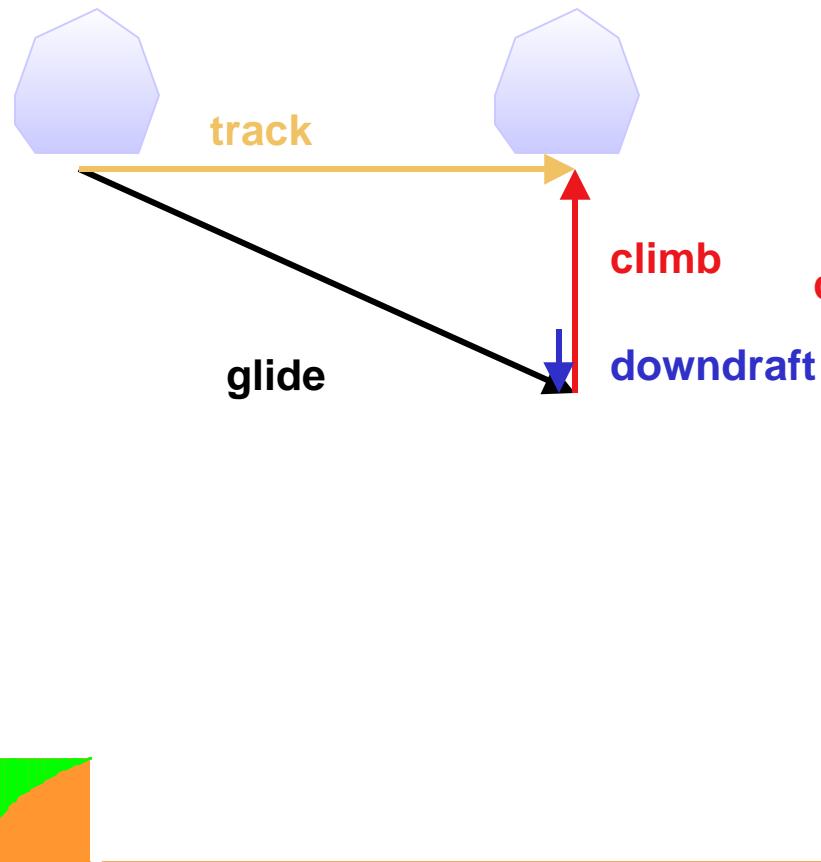
# Approach

- Wind induces airmass vertical motion in aligned patterns
- Speed-to-fly theory with airmass vertical motion during the glide

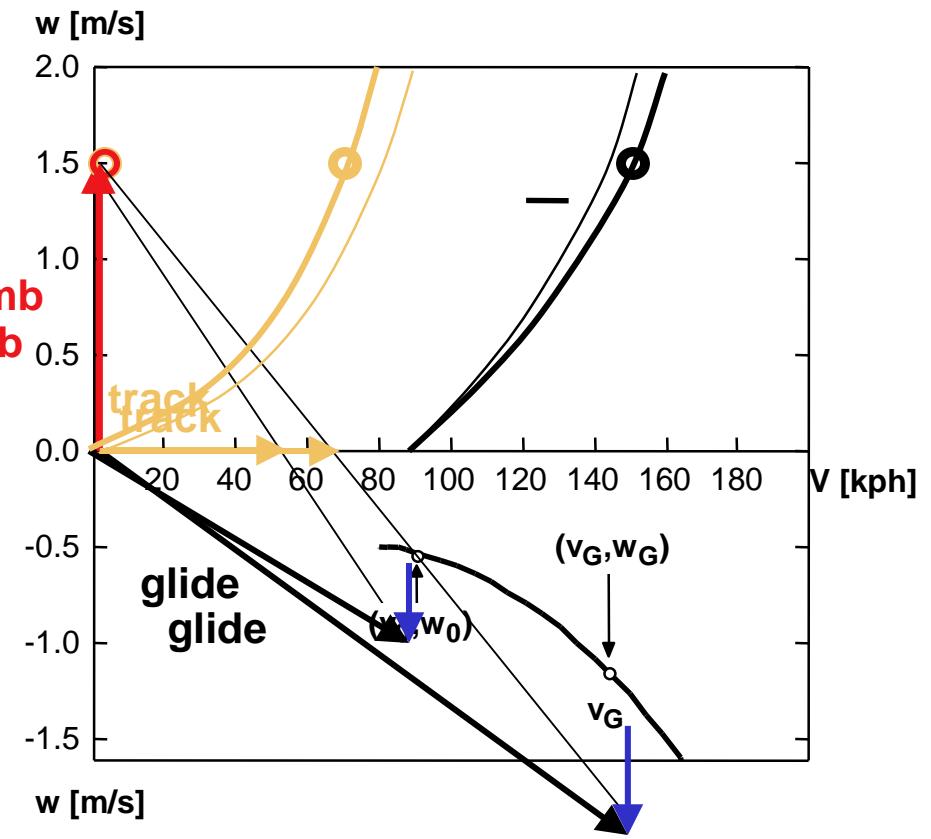


# Speed-to-fly in sinking airmass

## Path vectors

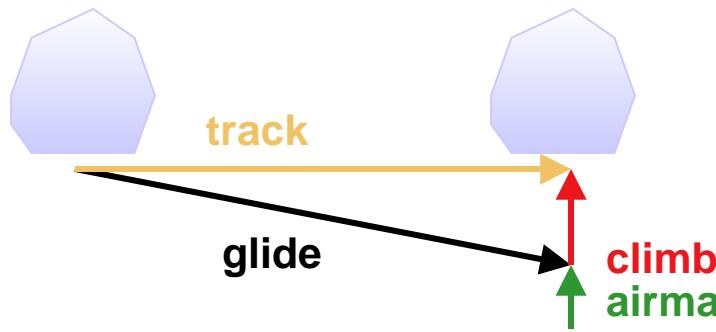


## Speed vectors



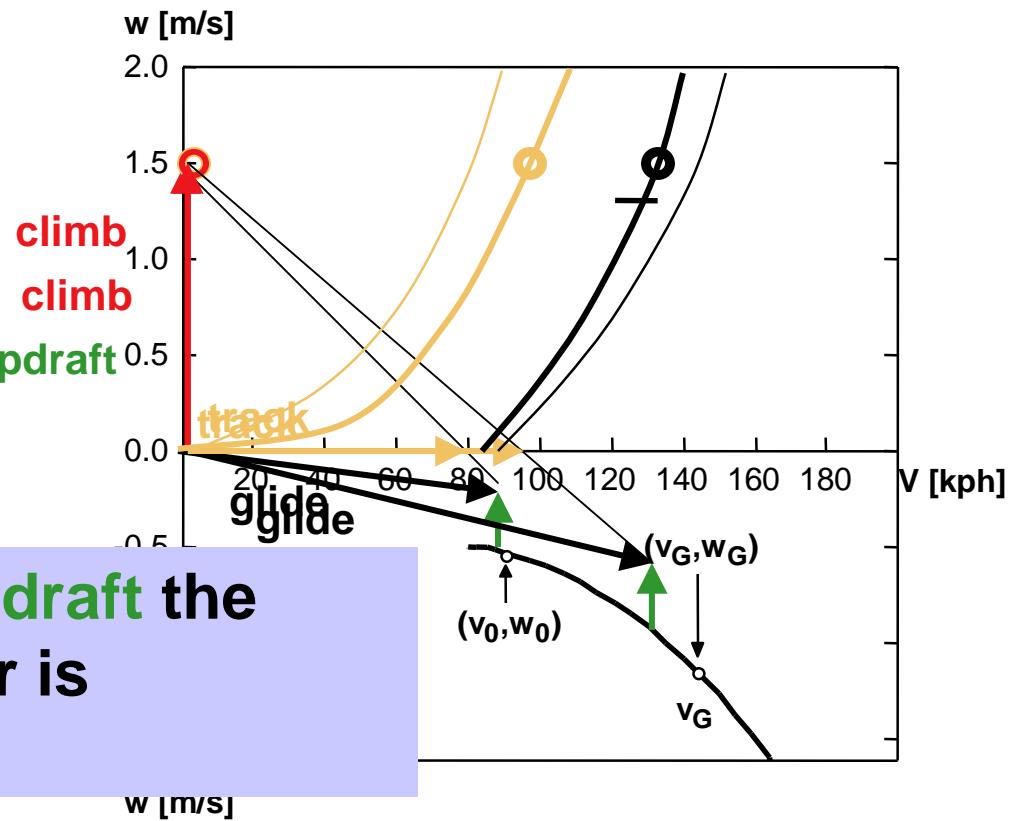
# Speed-to-fly in rising airmass

## Path vectors



With sufficient airmass updraft the minimum sink of the glider is compensated ....

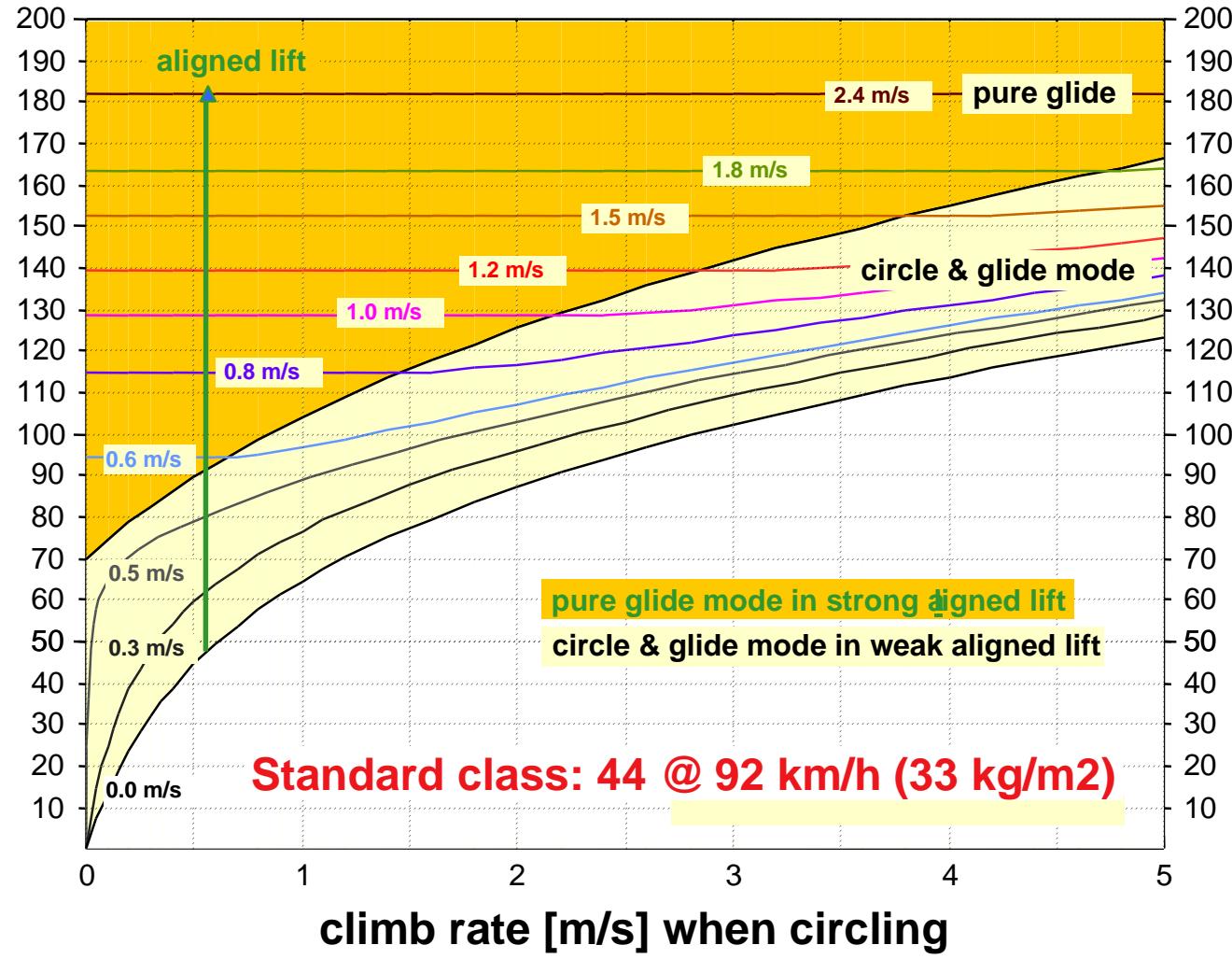
## Speed vectors



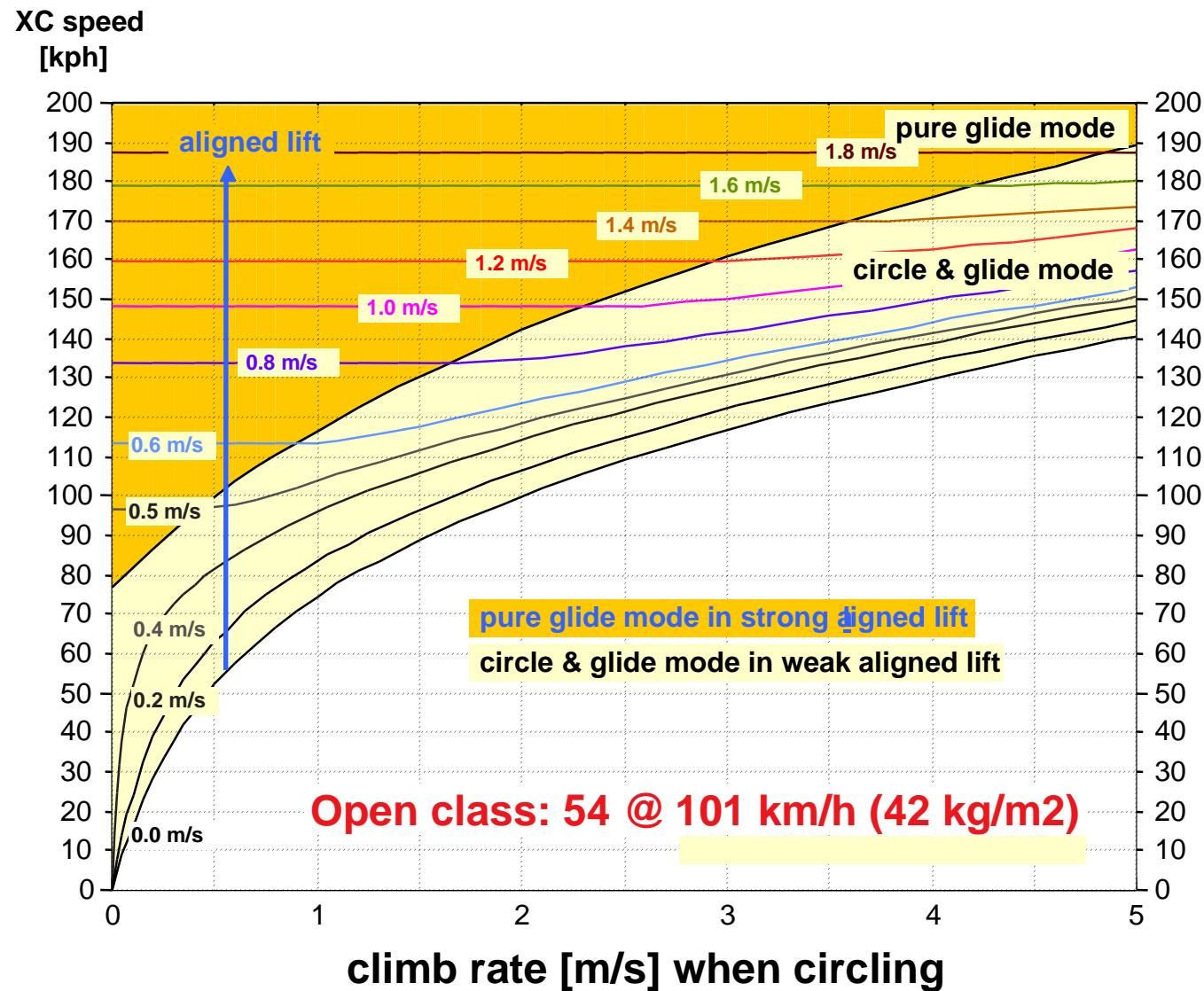
# $V_{\text{Track}}$ in rising airmass (standard class)

track speed

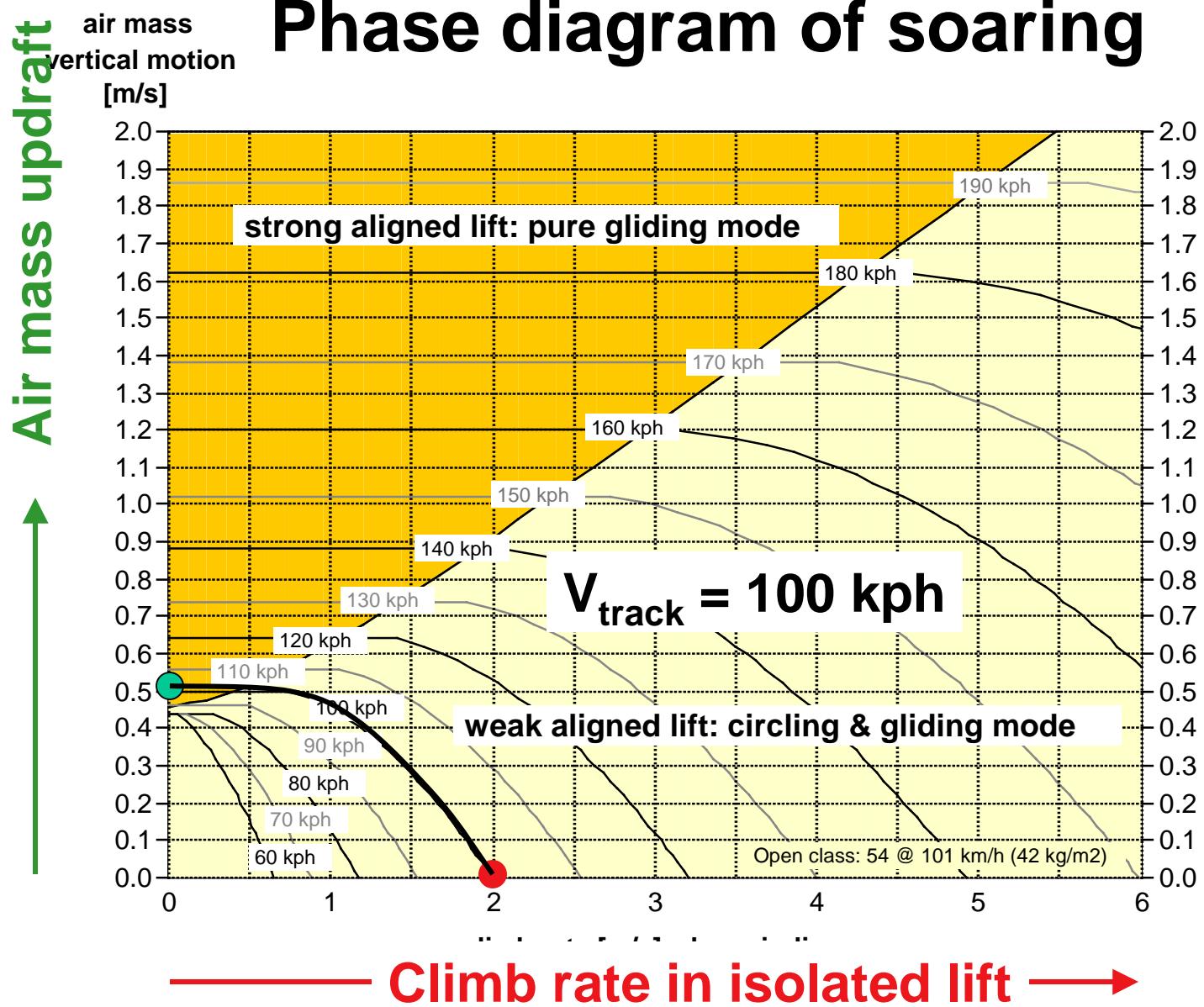
[kph]



# $V_{track}$ in rising airmass (Open class)



# Phase diagram of soaring



# Summary

- Speed-to-fly theory for isolated **lift** can be extended to **aligned lift**
- The time fraction spent climbing is the order parameter controlling the phase transition from „**climb&glide mode**“ to „**pure glide mode**“
- Predicted aligned lift can be used for flight planning ... **How about such predictions?**

